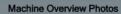
Sample Machine Risk Assessment Report Output





				Machi	ine & Ass	essment Details	3						
Machine Description	Flow Wrapper								Photo Re	f LWH	Inspectio	n Date	10/07/2019
Department	Bar Line		Area Packing								Asse	t Code	
Author	Risk Assessor				Con	pleted With (Pe	ersonnel Name)	John Jones					
Physical Limits of the Machine Risk Assessment	As per the physical limits of the flow wra	pper					ts of the ine Risk essment	surrounding ac	tivities. Hazards l	ant hazards directions assessed de trip hazards. Only	not include ma	anual handlin	g related hazards,
				Opera	iting Lifec	ycle Information	1						
General Equipment & Process Desc	Standard Campbell flow wrapper used to	wrap, seal and	cut plastic film	around bars. A series	s of in-feed	belt conveyors tra	ansport b	ars from the accu	ımulator, rotate th	em 90°, then acc	umulate and qu	eue them for	the flow wrapper stage
Start Up	Film is loaded onto an overhead mandre is loaded onto the feed conveyor and the			nto the sealing section	n. Product	(Cleaning	Manually wiped	d down				
Normal Operation	Runs continuously providing product is a	ontinuously providing product is available. If product flow stops, the wrapper process stops.				Trouble S	Shooting			ever access into t cutting bars is like			chine to clear mis-fed
End of Run	No special activities - product is run out	nd machine is turned off				Main	tenance	Periodic checki	ing of drive chain	s and sprocket co	ndition as well a	s lubrication	is required
General Comments	Type C standard EN 415-3 and AS/NZS	4024 has been	used as the ma	ain reference docume	ent for this	MRA							
					Existing	Controls							
Fixed Guards	The flow wrapper is fitted with a combina	ation of fixed and	d interlocked gua	ards (not compliant).				An interlock is f		over the metering	g unit, the side v	vrap unit, an	d the guard over the
Warning Signs/Indication	Stickers positioned on fixed guards indic machine. A sticker positioned at the entr pushers.						E-Stops	stage, up to the		winding section. (n-feed/rotation/meteri at the operator control
Energy Source	Description	Photo	Significant Hazard?	Isolation De	vice	Designation Coding		Lockable		Required Isolati Current Isolatio		Suit	ably Identifiable
Electricity	Powers conveyors, fin sealing wheels, rotary end sealer, and heaters.	QVW	Yes	Electrical isolation	n switch			Yes	P	adlock through loo	kable device	Intuitively	easy to identify, but no labelled
	Remedial Work / Comments	Voltage and ha	azard labels, but	t nothing to indicate th	his is the m	ain isolator. Mear	ningful "m	ain isolator" labe	lling is required.				
Pneumatic	Powers pneumatic parts e.g. splicers, brakes, sealing pressure, printer head	WHM	Yes	Exhausting Isolation	ion Valve			Yes	P	adlock through loo	ckable device	No	t easy to identify
Filedifiatio	Remedial Work / Comments			valve is fitted to the in /s appear to be tee'd						ion of the isolator.	Meaningful lab	elling is requ	ired for pneumatic







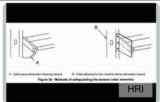






		Hazards,	, Risks and Controls Ass	essment							
		Description		Consequence	Source	Photo Ref					
Hazard Assessment		eumatic components such as the tension rolle ects, caused by accidental contact during dai		Broken or Dislocated Bones	Tools/Machinery						
Daw Diek	Raw	Risk Estimation (Risk Matrix)		Performance Level Assessment (NZS4024.1503)							
Raw Risk Assessment	Consequence Rating	Likelihood of Occurrence	Risk Score	Frequency of Exposure (more freq. than)	Possibility of Avoidance	PL Required					
7 iooooonion	Moderate (3)	Unlikely (2)	Moderate (6)	Daily	Possible	С					
	Hazard and Control Photos										





	VDI	HRI								
	Description		Status		Photo Ref	Control Type	Relevant	Standard	Budget Cost	Risk Reduction
	Emergency Stop fitted to operator control par	nel.	Existing			Engineering	EN 4	115-3		
	Local electrical isolation		Existing			N/A				
	Lockable exhausting isolation valve (not combeen tee'd off prior to the point of isolation.)	pliant since hose/s have	Existing			Engineering				
Controls	Pneumatic components are enclosed within roller arm is not compliant as it is external, ar from within the guards)		Existing			Engineering	AS/NZS	1024.1601		
Controls	Guarding required on each arm to prevent access to the hazard zone - refer to EN 415-3 for detail		Required		HRI, VDI	Engineering	EN 4	115-3	700	
	Meaningful isolator labelling is required.	Required			Signs, Labels, Markings	AS/NZ	S 4024	150		
	Site to investigate tee'd off air lines/hoses. All distribution should be after the isolation point. Any distribution prior to the isolation must be justified and isolated. Labelling must be clear and unambiguous as to respective isolator functions.		Required			Audit				
	Current Risk Estimation (Ris						Future Risk Es	timation (Risk N	Matrix)	
Current & Future RA	Consequence Rating	Likelihood of Oo	ccurrence	Ris	sk Score	Consequence Rating	g Likeliho		od of Occurrence	Risk Score
	Moderate (3)	Unlikely	(2)	Mod	derate (6)	Moderate (3)		Rare (1)		Low (3)
·										





Hazards, Risks and Controls Assessment Description Consequence Source Photo Ref Conveyor: Broken finger due to draw-in between belt and rollers/fixed objects caused by accidental start during cleaning/maintenance. **Hazard Assessment** Broken or Dislocated Bones Tools/Machinery Raw Risk Estimation (Risk Matrix) Performance Level Assessment (NZS4024.1503) Raw Risk Consequence Rating Likelihood of Occurrence Risk Score Frequency of Exposure (more freq. than) Possibility of Avoidance PL Required Assessment Moderate (3) Possible (3) Possible Moderate (9) Daily С Hazard and Control Photos







Covers enclose the outer radius and ends of the belt path, mitigating entry (not compliant since reach is possible into nip points and PBC created by guards). Local electrical isolation Existing Existing JIU, PYS, JLM Engineering AS/NZS 4024.1601 Engineering AS/NZS 4024.1601 Engineering AS/NZS 4024.1601 Engineering - Mechanical AS/NZS 4024.1601 1000 Engineering - Mechanical AS/NZS 4024.1601 1000			entry (not compliant since reach is possible in								
Controls Prevent contact with in-running pulley nips by closing residual guarding gaps to within 5mm in accordance with AS/NZS 4024.3610 as suitable risk reduction controls. Required Engineering - Mechanical AS/NZS 4024.1601 1000			created by guards). Local electrical isolation Prevent contact with in-running pulley nips by closing residual		Existing	JIU, PYS, JLM	Engineering	AS/NZS 4	4024.1601		
Controls guarding gaps to within 5mm in accordance with AS/NZS 4024.3610 as suitable risk reduction controls. Required Engineering - Mechanical AS/NZS 4024.1601 1000			Local electrical isolation		Existing		Engineering	AS/NZ	S 4024		
	Controls	Controls	guarding gaps to within 5mm in accordance		Required		Engineering - Mechanical	AS/NZS 4	4024.1601	1000	
Conveyor: Install additional Emergency Stop coverage for the ends and drive section of the 90° conveyor in accordance with AS/NZS 4024.3610. Coverage might be achieved simply by extending the non switch end of the existing flow wrapper pull-wire (budgeted).	Condo	4024.3610. Coverage might be achieved simply by extending the non		Cross Referer	nce	Engineering - Functional Safety	AS/NZS 4	1024.1604			
Current Risk Estimation (Risk Matrix) Future Risk Estimation (Risk Matrix)			Curren	nt Risk Estimation (Risk	(Matrix)		Future Risk Est		timation (Risk M	fatrix)	
Current & Future RA Consequence Rating Likelihood of Occurrence Risk Score Consequence Rating Likelihood of Occurrence Risk Score	Current & Future RA	nt & Future RA	Consequence Rating	Likelihood of Oc	ccurrence	Risk Score	Consequence Rating	1	Likelihoo	od of Occurrence	Risk Score
Moderate (3) Unlikely (2) Moderate (6) Moderate (3) Rare (1)			Moderate (3)	Unlikely	(2)	Moderate (6)	Moderate (3)			Rare (1)	Low (3)





			Hazards,	Risks a	nd Controls Ass	sessment				
		Description				Consequence			Source	Photo Ref
Hazard Assessment	Conveyor: Broken finger due to draw-in po guards, belt transitions),				(e.g. supports,	Broken or Dislocated Bo	nes	Too	ols/Machinery	
Daw Diek	Raw	Risk Estimation (Risk M	Matrix)			Perfor	mance Level A	ssessment (NZ	S4024.1503)	
Assessment	Consequence Rating	Likelihood of Oo	currence	F	Risk Score	Frequency of Exposure (more freq. than)		Possibility of Avoidance		PL Required
7	Moderate (3)	Possible	(3)	M	oderate (9)	Daily	Daily		Possible	С
			H	azard ar	nd Control Photo	os				
	Description	Description It has greater than 60mm deflection above support rollers. It surfaces are smooth, reducing the risk of drawing in. Inveyor is synchronised with the wrapper conveyor, providing a able risk reduction control measure. It electrical isolation It is a support to be greater than 120mm in accordance with NZS 4024.3610. Alternatively, install a tunnel guard in ordance with NZS 4024.1801 over the transition to prevent			Photo Ref	Control Type	Relevant	Standard	Budget Cost	Risk Reduction
	Belt has greater than 60mm deflection above	support rollers.	Existing			Engineering				
	Belt surfaces are smooth, reducing the risk of	of drawing in.	Existing			Engineering				
	Conveyor is synchronised with the wrapper of suitable risk reduction control measure.	Existing			Engineering					
Raw Risk Assessment Belt has Belt surf Conveyor suitable Local ele Prevent aligner a AS/NZS accorda contact. Install ac section o Coverage	Local electrical isolation		Existing			Engineering - Electrical	AS/NZ	ZS 3000		
Controls	Prevent arm drawing in/crushing by increase the gap between the aligner and conveyor to be greater than 120mm in accordance with AS/NZS 4024.3610. Alternatively, install a tunnel guard in accordance with AS/NZS 4024.1801 over the transition to prevent contact.		Required			Engineering - Mechanical	AS/NZ	ZS 4024	1500	
		Cross Refere	nce		Engineering - Functional Safety	AS/NZS	4024.1604			
	Currer	t Risk Estimation (Risk	Matrix)				Future Risk Es	stimation (Risk N	Matrix)	
Current & Future RA	Consequence Rating	Likelihood of Oo	currence	F	Risk Score	Consequence Rating	1	Likeliho	od of Occurrence	Risk Score
	Moderate (3)	Unlikely ((2)	M	oderate (6)	Moderate (3)			Rare (1)	Low (3)





The second		Hazards,	, Risks and Controls Ass	sessment							
		Description		Consequence	Source	Photo Ref					
Hazard Assessment	Finger amputation due to chain/belt/trans	mission nip and shearing points caused by un cleaning or maintenance.	expected startup during	Amputation	Tools/Machinery						
Daw Diek	Raw	Risk Estimation (Risk Matrix)		Performance Level Assessment (NZS4024.1503)							
Raw Risk Assessment	Consequence Rating	Likelihood of Occurrence	Risk Score	Frequency of Exposure (more freq. than)	Possibility of Avoidance	PL Required					
7 ISSOCIATION	Major (4) Possible (3)		High (12)	Monthly	Possible	С					
	Hazard and Control Photos										













	Description		Status	Photo Ref	Control Type	Relevant	Standard	Budget Cost	Risk
	Conveyor: A fixed guard is fitted over the out accidental contact (marginally non-compliant possible).		Existing	SGM	Engineering	AS/NZS	4024.1601	•	Reduction
	Emergency Stop pull wire installed along the section of the flow wrapper (not compliant as for the 90° conveyor)		Existing		Engineering	EN 4	415-3		
	Fixed guards are fitted along the front of the around certain hazards (not compliant as acc gaps underneath guards - e.g, by reaching th through holes in fixed guards).	ess is possible through	Existing	GMI, QVP, PGM, IWO, YYN	Engineering				
	Local electrical isolation		Existing		Engineering				
	Conveyor: Improve fixed guarding in accorda 4024.1801 prevent contact with output shaft.	nce with AS/NZS	Required		Engineering - Mechanical	AS/NZS	4024.1801	500	
	Conveyor: Install additional Emergency Stop coverage for the ends and drive section of the 90° conveyor in accordance with AS/NZS 4024.3610. Coverage might be achieved simply by extending the non-switch end of the existing flow wrapper pull-wire (budgeted).		Required		Engineering - Functional Safety	AS/NZS	4024.1604	500	
	Meaningful isolator labelling is required.		Required		Signs, Labels, Markings	AS/NZ	S 4024	150	
	Prevent contact with transmission/belt/chain hazards by installing additional guarding in accordance with AS/NZS 4024.1801. Up to 30x30mm square mesh or 20mm slots may be suitable if they are at least 120mm away from hazards.		Required		Engineering - Mechanical	EN 4	415-3	2400	Medium
	Curren	t Risk Estimation (Risk	Matrix)			Future Risk Es	timation (Risk M	latrix)	
urrent & Future RA	Consequence Rating	Likelihood of Oc	currence	Risk Score	Consequence Rating		Likelihoo	od of Occurrence	Risk Score
	Major (4)	Unlikely (2)	Moderate (8)	Major (4)			Rare (1)	Moderate (4





	Hazards, Risks and Controls Assessment											
		Description		Consequence	Source	Photo Ref						
Hazard Assessment	i inger ampatation add to ocamig catting jan	s crushing shearing hazard to hands/fingers on e film cutting and sealing jaws	due to the closing action of	Amputation e.g. Fingers, Hand, Foot, Arm, Leg	Tools/Machinery							
Daw Diak	Raw	Risk Estimation (Risk Matrix)		Performance Level Assessment (NZS4024.1503)								
Raw Risk Assessment	Consequence Rating	Likelihood of Occurrence	Risk Score	Frequency of Exposure (more freq. than)	Possibility of Avoidance	PL Required						
7 ISSOCIATION	Major (4)	Possible (3)	High (12)	Daily	Possible	С						
	Hazard and Control Photos											



	Description		Status	Photo Re	f Control Type	Relevant S	Standard	Budget Cost	Risk Reduction
	Emergency Stop within 2m of the sealing hea	ad.	Existing		Engineering	EN 41	5-3		
	Existing locked interlocked guarding design I to the hazard zone (not compliant as it does both sides). If the machine is powered down safety system cannot reset until the guard is	not prevent contact - the lock is released. The	Existing	SIF	Engineering	EN 41	5-3		
Controlo	Controls Local electrical isolation Prevent contact with the sealing laws from either s		Existing		Engineering				
Controls	Prevent contact with the sealing jaws from either side and all residual apertures. Install additional fixed guarding in accordance with AS/NZS 4024.1801 to both in- and out-feed apertures. An aperture height of up to 20mm may be suitable. A reach distance of at least 850mm will be required if this is not achievable. Residual apertures must be closed up with fixed guarding in accordance with AS/NZS 4024.1801.		Required		Engineering	EN 41	5-3	500	
	Current Risk Estimation (Risk Matrix)					Future Risk Estir	mation (Risk M	Matrix)	
Current & Future RA	Consequence Rating	Likelihood of Oo	currence	Risk Score	Consequence Ra	ting	Likelihood of Occurrence		Risk Score
	Major (4)	Unlikely	(2)	Moderate (8)	Major (4)		Rare (1)		Moderate (4)





111111111111111111111111111111111111111		Hazards,	Risks and Controls Asse	essment					
		Description		Consequence	Source	Ph			
Hazard Assessment	Fingertip amputation due to crushing/shearing by unex	ng as feed chain lugs pass fixed objects (e.g. g pected startup during maintenance.	guards/apertures), caused	Amputation - Fingertip (no bone)	Tools/Machinery				
Daw Diek	Raw	Risk Estimation (Risk Matrix)		Performance Level Assessment (NZS4024.1503)					
Raw Risk Assessment	Consequence Rating	Likelihood of Occurrence	Risk Score	Frequency of Exposure (more freq. than)	Possibility of Avoidance	PL Required			
Assessment	Moderate (3)	Possible (3)	Moderate (9)	Daily	Possible	С			
Hazard and Control Photos									







									Risk
	Description		Status	Photo Ref	Control Type	Relevant	Standard	Budget Cost	Reduction
	Emergency Stop pull wire installed along the section.	length of the in-feed	Existing		Engineering	EN 4	415-3		
	Existing guarding design reduces the risk of zone (not compliant as reach is generally not or through aperture)		Existing	HGB, GJP, DHD	Engineering	EN	415-3		
	Local electrical isolation		Existing		Engineering				
	Prevent lugs shearing fingers if they are inserted through the head aperture - install an internal tunnel guard. A cheek plate on each side of the lug path within 5mm in accordance with AS/NZS 4024.1801 and AS/NZS 4024.3610 is likely suitable.		Required		Engineering - Mechanical	AS/NZS	4024.1801	500	
	Prevent contact with transmission/belt/chain hazards by installing additional guarding in accordance with AS/NZS 4024.1801. Up to 30x30mm square mesh or 20mm slots may be suitable.		Cross Referer	nce	Engineering - Mechanical	EN 4	415-3		
	Curren	t Risk Estimation (Risk	Matrix)			Future Risk Es	timation (Risk N	Matrix)	
Current & Future RA	Consequence Rating	Likelihood of Oc	currence	Risk Score	Consequence Rating	9	Likeliho	od of Occurrence	Risk Score
	Moderate (3)	Unlikely (2)	Moderate (6)	Moderate (3)			Rare (1)	Low (3)





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About The MinRisk App

The MinRisk App is built by Safety Engineers, for Health and Safety teams.

Focusing on the specific issue of machine safety assessment, the team at TEG Risk has a deep understanding of machine safety and risk assessment through its consulting and project management businesses. The TEG Risk team created The MinRisk App to support their inhouse consulting team, and after 6 years of research and development, are bringing it to market, to better serve Health and Safety and Engineering teams, in the manufacturing sector.

Pricing and contact



The MinRisk App Licence Fees

We charge depending on the number of sites, machines and users you have. Our flexible pricing allows for read-only access for senior management and multiple administrators if needed.



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